METAPOT ROTARY MEMBRANE SENSOR MTP-R

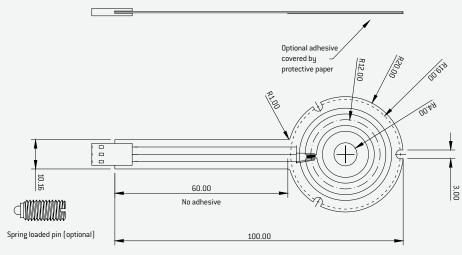


systems. The rotary membrane sensors are ideal for use in precision positioning applications in many applications.

- IP65
- Optional: Adhesive backing

- Rotary position sensing





ELECTRICAL SPECIFICATIONS			
Resistance range (Rn)	2.5 k Ω / 25 mm perimeter		
Resistance tolerance	± 30 %		
Electrical angle	25° – 345°		
Independent linearity	± 2 % **		
Resolution	< 0.05 mm perimeter **		
Maximum wiper current	5 mA in case of malfunction		
Typical supply voltage	3 – 30 VDC		
Wiper load	> 100 x Rn		
Spring loaded pin	Mechanical wiper pin as M6 threaded part with spring-loaded ball		

Mechanical and electrical characteristics are customizable. Specifications are subject to change without notice. * Others on request. ** Specifications may deviate according to temperature and installation conditions.

MECHANICAL SPECIFICATIONS		
Lifetime	> 5 million cycles **	
Max. travel speed	0.1 m/s **	
Sensor thickness	0.5 mm	
Actuation force	1-3 N **	
Wiper	See mounting recommendation for MTP	
AMBIENT CONDITIONS		
Operating temperature	−25°C+85°C**	
Protection class	IP65 according to DIN EN 60529, electrical connection and plug excluded	
MATERIALS		
Substrates	PET polyester film, FR4	
Electrical connectors	Female crimp contacts, Crimpflex solder tabs * (Poka Yoke)	

SAMPLE ORDER				
Part no.	Type series	Resistance range	Elect. measuring range	Elect. connection
E080200345	MTP-R	2.5 K	345°*	Female crimp contacts
H959000000	Spring loaded pin			

MOUNTING RECOMMENDATION FOR MTP-L, MTP-R, MTP-LX



Selecting the correct type of actuation and the correct materials is essential for ensuring the operational reliability of our MetaPot membrane sensors. Below, you will find the most important information for mounting. Our development team will be happy to assist you with your application.







PREPARING THE SURFACE

- The surface on which the membrane sensor is to be mounted has to be free of moisture, oil, grease and dust. Avoid change in temperature between the membrane sensor and the supporting surface.
- In addition, the surface should be flat in order to ensure faultless mounting and operation of the membrane sensor.
- Depending on the material of the supporting surface, isopropanol or butanone may be used as a cleaning agent.

MATERIALS	BALL	SPRING FORCE
POM/Stainless steel	R 8 – 10 mm	0.5 N –5 N *

* Contact force: The contact force is the force required in order to establish the first electrical contact. Optimal spring force: =1.5 x contact force

EXAMPLE:	
Contact force	0.4 N
Max. contact force	5 N

FACTORS THAT INFLUENCE THE SPRING FORCE:

- Active measuring width
- Film material
- Travel speed

